

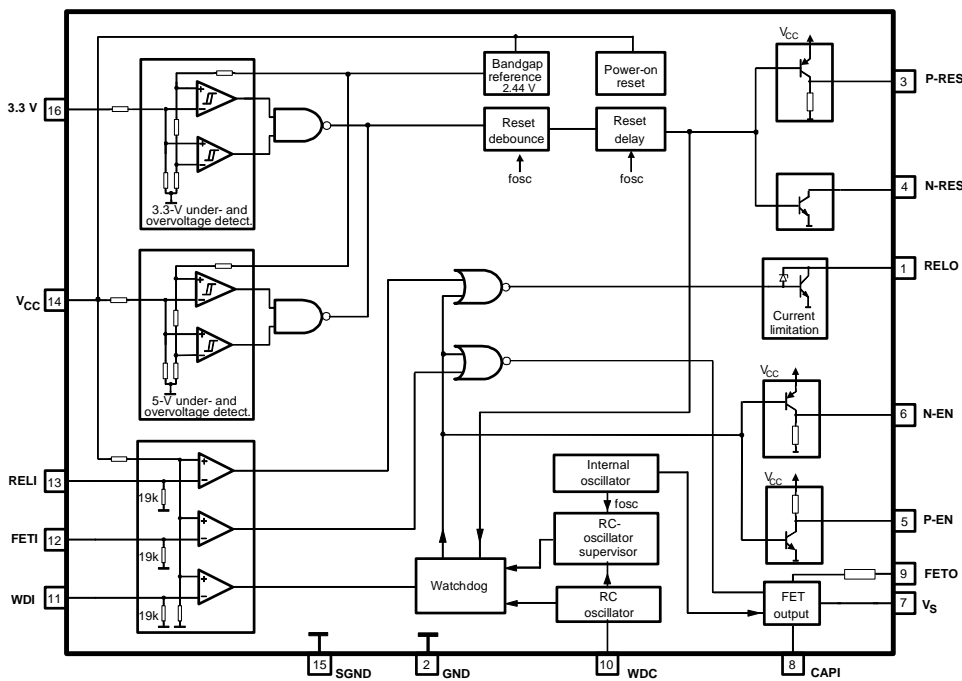
Features

- Digital Self-supervising Watchdog with Hysteresis
- One 150-mA Output Driver for Relay
- One High-side Driver for N-channel Power FET
- Positive and Negative Enable Output
- Positive and Negative Reset Output
- Over/Under-voltage Detection
- Relay and Power FET Outputs Protected Against Standard Transients and 55-V Load Dump

Description

The function of microcontrollers in safety-critical applications (e.g., anti-lock systems) needs to be monitored permanently. Usually, this task is accomplished by an independent watchdog timer. The monolithic IC U6813B, designed in bipolar technology and qualified according to the needs of the automotive industry, includes such a watchdog timer and provides additional features for added value. With the help of integrated driver stages, it is easy to control safety-related functions of a relay and of an N-channel power MOSFET in high-side applications. In case of a microcontroller malfunction or supply-voltage anomalies, the U6813B provides positive and negative reset and enable output signals. This flexibility guarantees a broad range of applications. The U6813B is based on of Atmel's fail-safe ICs U6808B and U6809B.

Figure 1. Block Diagram

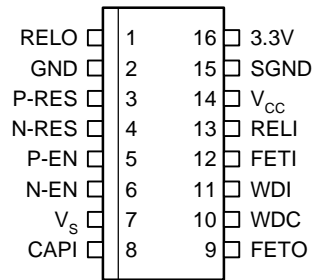


Fail-safe IC with High-side and Relay Driver

U6813B

Pin Configuration

Figure 2. Pinning SO16



Pin Description

| Pin | Symbol | Description | Function | Type |
|-----|-----------------|------------------------------|---|----------------|
| 1 | RELO | Open-collector output driver | Fail-safe relay driver | Driver on: L |
| 2 | GND | Supply | General ground | |
| 3 | P-RES | Digital output | Positive reset signal | Reset: H |
| 4 | N-RES | Digital output | Negative reset signal | Reset: L |
| 5 | P-EN | Digital output | Positive enable signal | Enable: H |
| 6 | N-EN | Digital output | Negative enable signal | Enable: L |
| 7 | V _S | Battery supply | Voltage for charge pump | |
| 8 | CAPI | Analog input | Input bootstrap capacitor | |
| 9 | FETO | Power FET output | High voltage for N-channel FET | |
| 10 | WDC | Analog input | External RC for watchdog timer | |
| 11 | WDI | Digital input | Watchdog trigger signal | Pulse sequence |
| 12 | FETI | Digital input | Activation of power FET | FET on: H |
| 13 | RELI | Digital input | Activation of relay driver | Driver on: H |
| 14 | V _{CC} | Supply | 5-V supply | |
| 15 | SGND | Supply | Sense ground, reference for V _{CC} and 3.3 V | |
| 16 | 3.3V | Analog input | 3.3-V supply | |

Fail-safe Functions

A fail-safe IC has to maintain its monitoring function even if there is a fault condition at one of the pins (e.g., short circuit), ensuring that a microcontroller system does not reach a “critical status”. A critical status means, for example, if the system is not able to switch off the relay or disable the power MOSFET, or if the system is not able to provide a signal to the microcontroller via ENABLE- and RESET-outputs in the case of a fault condition. The U6813B is designed to handle those fault conditions according to Table 1 for a maximum of system safety.

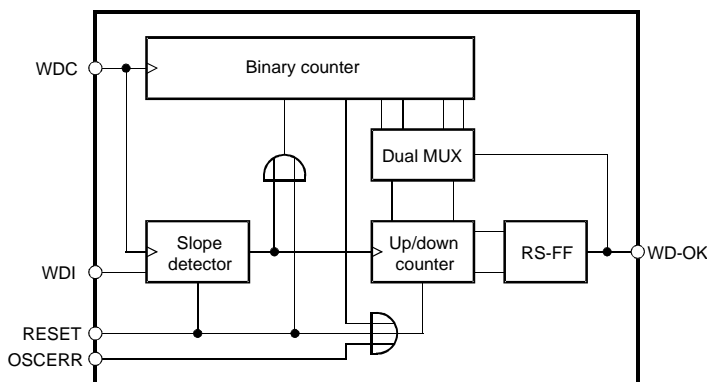
Table 1. Truth Table

| VCC | 3.3V | WDI | RELI | FETI | RELO | FETO | N-RES | P-RES | P-EN ⁽²⁾ | N-EN ⁽³⁾ |
|-------|-------|-------|------------------|------------------|------|------|-------|-------|---------------------|---------------------|
| ok | ok | ok | H | x | on | x | H | L | H | L |
| ok | ok | ok | L ⁽¹⁾ | x | off | x | H | L | H | L |
| ok | ok | ok | x | H | x | on | H | L | H | L |
| ok | ok | ok | x | L ⁽¹⁾ | x | off | H | L | H | L |
| ok | ok | wrong | x | x | off | off | H | L | L | H |
| x | wrong | x | x | x | off | off | L | H | L | H |
| wrong | x | x | x | x | off | off | L | H | L | H |

Notes: 1. default state at open input
 2. P-EN disable: low
 3. N-EN disable: high

Watchdog Description

Figure 3. Watchdog Block Diagram



The microcontroller is monitored by a digital window watchdog which accepts an incoming trigger signal of a constant frequency for correct operation. The frequency of the trigger signal can be varied in a broad range as the watchdog's time window is determined by external R/C components. The following description refers to the watchdog timing diagram with tolerances (see Figure 4).

WDI Input (Pin 11)

The microcontroller has to provide a trigger signal with the frequency f_{WDI} which is fed to the WDI input. A positive edge of f_{WDI} detected by a slope detector resets the binary counter and clocks the up/down counter. The latter one counts only from 0 to 3 or reverse. Each correct trigger increments the up/down counter by 1, each wrong trigger decrements it by 1. As soon as the counter reaches status 3, the RS flip-flop is set; see Figure 5 (Watchdog state diagram). A missing incoming trigger signal is detected after 250 clocks of the internal watchdog frequency f_{RC} (see WD_OK output) and resets the up/down counter directly.

WDC Input (Pin 10)

It is to be equipped by external R/C components. By means of an external R/C circuitry, the IC generates a time base (frequency f_{WDC}) independent from the microcontroller. The watchdog's time window refers to a frequency of $f_{WDC} = 100 \times f_{WDI}$.

OSCERR Input

A smart watchdog has to ensure that internal problems with its own time base are detected and do not lead to an undesired status of the complete system. If the RC oscillator stops oscillating, a signal is fed to the OSCERR input after a timeout delay. It resets the up/down counter and disables the WD-OK output. Without this reset function, the watchdog would freeze its current status when f_{RC} stops.

RESET Input

During power-on and under/overvoltage detection, a reset signal is fed to this pin. It resets the watchdog timer and sets the initial state.

WD-OK Output

After the up/down counter has reached to status 3 (see Figure 5, Watchdog State Diagram), the RS flip-flop is set and the WD-OK output becomes logic "1". As WD-OK is directly connected to the enable pins, the open-collector output P-EN provides also logic "1" while a logic "0" is available at N-EN output. If on the other hand the up/down counter is decremented to "0", the RS flip-flop is reset, the WD-OK output and the P-EN output are logic "0" and N-EN output is logic "1". The WD-OK output also controls a dual MUX stage which shifts the time window by one clock after a successful trigger, thus forming a hysteresis to provide stable conditions for the evaluation of the trigger signal "good or false". The WD-OK signal is also reset in case the watchdog counter is not reset after 250 clocks (missing trigger signal).

Figure 4. Watchdog Timing Diagram with Tolerances

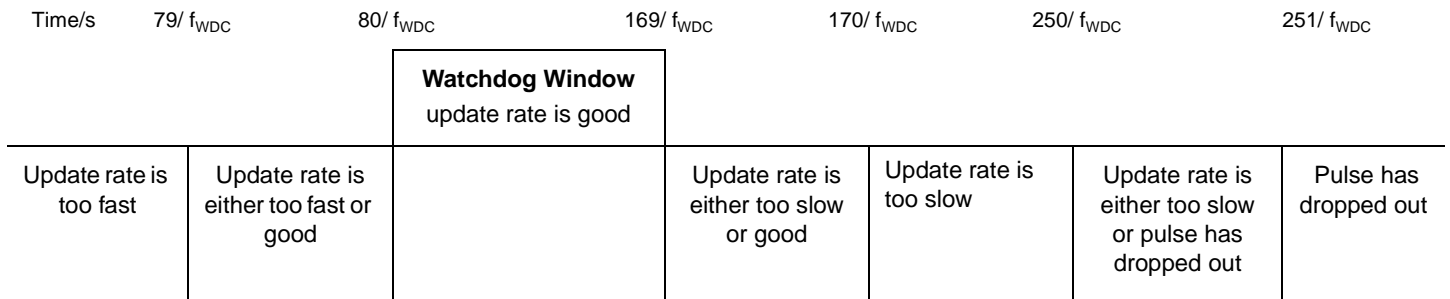
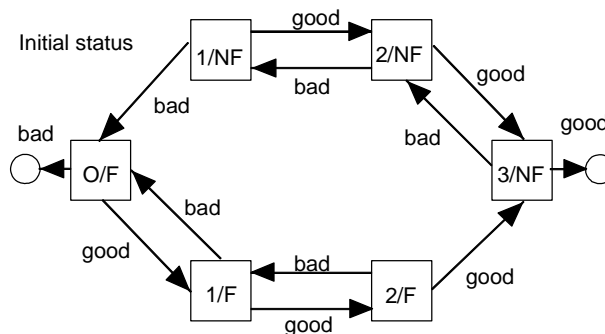


Figure 5. Watchdog State Diagram



Explanation

In each block, the first character represents the state of the counter. The second notation indicates the fault status of the counter. A fault status is indicated by an "F" and a no-fault status is indicated by an "NF". When the watchdog is powered up initially, the counter starts at the 0/F block (initial state). "Good" indicates that a pulse has been received whose width resides within the timing window. "Bad" indicates that a pulse has been received whose width is either too short or too long.

Watchdog Window Calculation

Example with recommended values

$C_{osc} = 6.8 \text{ nF}$ (should be preferably 10%, NPO)

$R_{osc} = 36 \text{ k}\Omega$ (can be 5%, $R_{osc} < 200 \text{ k}\Omega$ due to leakage current and humidity)

RC oscillator

$$t_{WDC} \text{ (s)} = 10^{-3} [C_{osc} \text{ (nF)} [(0.00078 R_{osc} \text{ (k}\Omega) + 0.0005)]]$$

$$f_{WDC} \text{ (Hz)} = 1 / (t_{WDC})$$

Watchdog WDI

$$f_{WDI} \text{ (Hz)} = 0.01 f_{WDC}$$

$$t_{WDC} = 200 \text{ }\mu\text{s} \rightarrow f_{WDC} = 5 \text{ kHz}$$

$$f_{WDI} = 50 \text{ Hz} \rightarrow t_{WDI} = 20 \text{ ms}$$

WDI pulse width for fault detection after 3 pulses:

Upper watchdog window

$$\text{Minimum: } 169 / f_{WDC} = 33.8 \text{ ms} \rightarrow f_{WDC} / 169 = 29.55 \text{ Hz}$$

$$\text{Maximum: } 170 / f_{WDC} = 34 \text{ ms} \rightarrow f_{WDC} / 170 = 29.4 \text{ Hz}$$

Lower watchdog window

$$\text{Minimum: } 79 / f_{WDC} = 15.8 \text{ ms} \rightarrow f_{WDC} / 79 = 63.3 \text{ Hz}$$

$$\text{Maximum: } 80 / f_{WDC} = 16 \text{ ms} \rightarrow f_{WDC} / 80 = 62.5 \text{ Hz}$$

WDI dropouts for immediate fault detection:

$$\text{Minimum: } 250 / f_{WDC} = 50.0 \text{ ms}$$

$$\text{Maximum: } 251 / f_{WDC} = 50.2 \text{ ms}$$

Remarks to reset relay

The duration of the over- or undervoltage pulses determines the enable- and reset outputs. A pulse duration shorter than the debounce time has no effect on the outputs. A pulse longer than the debounce time results in the first reset delay. If a pulse appears during this delay, a second delay time is triggered. Therefore, the total reset delay time can be longer than specified in the data sheet.

Absolute Maximum Ratings

| Parameters | Symbol | Value | Unit |
|---------------------------|-----------|---|------------------|
| Supply voltage range | V_S | - 0.2 to +26 | V |
| Power dissipation | P_{tot} | $V_S = 5\text{ V}; T_{amb} = -40^\circ\text{C}$ | 250 |
| | | $V_S = 5\text{ V}; T_{amb} = 125^\circ\text{C}$ | 150 |
| Junction temperature | T_j | 150 | $^\circ\text{C}$ |
| Ambient temperature range | T_{amb} | -40 to +125 | $^\circ\text{C}$ |
| Storage temperature range | T_{stg} | -55 to +155 | $^\circ\text{C}$ |

Thermal Resistance

| Parameters | Symbol | Value | Unit |
|------------------|------------|-------|------|
| Junction ambient | R_{thJA} | 110 | K/W |

Electrical Characteristics

$V_{CC} = 5\text{ V}$, $T_{amb} = -40\text{ to }+125^\circ\text{C}$; reference pin is GND or SGND (over- and under-voltage detection);
 $f_{intern} = 200\text{ kHz } +50\%/-45\%$, $f_{WDC} = 5\text{ kHz } \pm 10\%$; $f_{WDI} = 50\text{ Hz}$, bootstrap capacitor $C_{Boot} = 47\text{ nF}$ at Pin CAPI

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
|----------|--|---|-----|----------------------|---------------------|------|-------------------------|---------------|-------|
| 1 | Supply | | | | | | | | |
| 1.1 | Operation-voltage range | | 14 | V_{CC} | 4.5 | | 5.5 | V | D |
| 1.2 | Operation-voltage range of RESET outputs | | 14 | V_{CC} | 1.1 | | 18.0 | V | A |
| 1.3 | Current consumption | $V = 5.25\text{ V}$, Relay on $T_{amb} = -40^\circ\text{C}$ $T_{amb} = +125^\circ\text{C}$ | 14 | I_{CC} I_{CC} | | | 15 10 | mA mA | A |
| 2 | Digital Input WDI | | | | | | | | |
| 2.1 | Detection low | | 11 | V_{WDI} | -0.2 | | $0.3 \times V_{CC}$ | V | D |
| 2.2 | Detection high | | 11 | V_{WDI} | $0.7 \times V_{CC}$ | | $V_{CC} + 0.2\text{ V}$ | V | D |
| 2.3 | Internal pull-down resistor | | 11 | R_{INT11} | 10 | | 40 | $k\Omega$ | A |
| 2.4 | Input current low | Input voltage = 0 V | 11 | I_{WDI} | -5 | | 5 | μA | A |
| 2.5 | Input current high | Input voltage = 5 V | 11 | I_{WDI} | 100 | | 550 | μA | A |
| 3 | Digital Input RELI | | | | | | | | |
| 3.1 | Detection low | | 13 | V_{RELI} | -0.2 | | $0.3 \times V_{CC}$ | V | D |
| 3.2 | Detection high | | 13 | V_{RELI} | $0.7 \times V_{CC}$ | | $V_{CC} + 0.2\text{ V}$ | V | D |
| 3.3 | Internal pull-down resistor | | 13 | R_{INT13} | 10 | | 40 | $k\Omega$ | A |
| 3.4 | Input current low | Input voltage = 0 V | 13 | I_{RELI} | -5 | | 5 | μA | A |

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Note: 1. If $V_S > 26\text{ V}$ the current has to be limited at 5 mA by an external resistor.

Electrical Characteristics (Continued)

$V_{CC} = 5\text{ V}$, $T_{amb} = -40\text{ to }+125^{\circ}\text{C}$; reference pin is GND or SGND (over- and under-voltage detection);
 $f_{intern} = 200\text{ kHz }+50\%/-45\%$, $f_{WDC} = 5\text{ kHz } \pm 10\%$; $f_{WDI} = 50\text{ Hz}$, bootstrap capacitor $C_{Boot} = 47\text{ nF}$ at Pin CAPI

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
|----------|--|--------------------------------|-----|-------------|-------------------------|------|-------------------------|------------------|-------|
| 3.5 | Input current high | Input voltage = 5 V | 13 | I_{RELI} | 100 | | 550 | μA | A |
| 4 | Digital Input FETI | | | | | | | | |
| 4.1 | Detection low | | 12 | V_{FETI} | -0.2 | | $0.3 \times V_{CC}$ | V | A |
| 4.2 | Detection high | | 12 | V_{FETI} | $0.7 \times V_{CC}$ | | $V_{CC} + 0.2\text{ V}$ | V | A |
| 4.3 | Internal pull-down resistor | | 12 | R_{INT12} | 10 | | 40 | $\text{k}\Omega$ | A |
| 4.4 | Input current low | Input voltage = 0 V | 12 | I_{FETI} | -5 | | 5 | μA | A |
| 4.5 | Input current high | Input voltage = 5 V | 12 | I_{FETI} | 100 | | 550 | μA | A |
| 5 | Digital Output N-RES (Open Collector) | | | | | | | | |
| 5.1 | Saturation voltage low | $I_{reset} \leq 2.5\text{ mA}$ | 4 | V_{SAT4} | | | 0.5 | V | A |
| 5.2 | Leakage current | at 5 V, high state | 4 | I_{LEAK4} | | | 0.5 | μA | A |
| 5.3 | Reset debounce time (switch to low) | Over- or undervoltage | 4 | t_{DEB4} | 120 | 320 | 500 | μs | A |
| 5.4 | Reset delay (switch back to high) | Over- or undervoltage | 4 | t_{DEL4} | | 50 | | ms | A |
| 6 | Digital Output P-RES (Internal Pull-down Resistor) | | | | | | | | |
| 6.1 | Saturation voltage high | $I_{reset} \leq 0.3\text{ mA}$ | 3 | V_{SAT3} | $V_{CC} - 0.5\text{ V}$ | | V_{CC} | V | A |
| 6.2 | Leakage current | at 0 V, low state | 3 | I_{LEAK3} | | | 0.5 | μA | A |
| 6.3 | Internal pull-down resistor | at 5 V | 3 | R_{INT3} | 25 | | 100 | $\text{k}\Omega$ | A |
| 6.4 | Reset debounce time (switch to low) | Over- or undervoltage | 3 | t_{DEB3} | 120 | 320 | 500 | μs | A |
| 6.5 | Reset delay (switch back to high) | Over- or undervoltage | 3 | t_{DEL3} | | 50 | | ms | A |
| 7 | Digital Output N-EN (with Open Collector and Internal Pull-down Resistor) | | | | | | | | |
| 7.1 | Saturation voltage high | $I \leq 1\text{ mA}$ | 6 | V_{SAT6} | $V_{CC} - 0.5\text{ V}$ | | V_{CC} | V | A |
| 7.2 | Leakage current | at 0 V, low state | 6 | I_{LEAK6} | | | 0.5 | μA | A |
| 7.3 | Internal pull-down resistor | at 5 V | 6 | R_{INT6} | 25 | | 100 | $\text{k}\Omega$ | A |
| 7.4 | Enable debounce time (switch to low) | Over- or undervoltage | 6 | t_{DEB6} | 120 | 320 | 500 | μs | A |
| 7.5 | Enable delay (switch back to high) | Over- or undervoltage | 6 | t_{DEL6} | | 85 | | ms | A |

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Note: 1. If $V_S > 26\text{ V}$ the current has to be limited at 5 mA by an external resistor.

Electrical Characteristics (Continued)

$V_{CC} = 5\text{ V}$, $T_{amb} = -40\text{ to }+125^{\circ}\text{C}$; reference pin is GND or SGND (over- and under-voltage detection);
 $f_{intern} = 200\text{ kHz } +50\%/ -45\%$, $f_{WDC} = 5\text{ kHz } \pm 10\%$; $f_{WDI} = 50\text{ Hz}$, bootstrap capacitor $C_{Boot} = 47\text{ nF}$ at Pin CAPI

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
|-----------|--|---|-----|----------------------------|---------------------|------|---------------------|--------------------------------|-------|
| 8 | Digital Output P-EN (Internal Pull-up Resistor) | | | | | | | | |
| 8.1 | Saturation voltage high | $I \leq 3\text{ mA}$ | 5 | V_{SAT5} | | | 0.5 | V | A |
| 8.2 | Leakage current | at 5 V, high state | 5 | I_{LEAK5} | | | 0.5 | μA | A |
| 8.3 | Internal pull-up resistor | at 0 V | 5 | R_{INT5} | 12.5 | | 50 | $\text{k}\Omega$ | A |
| 8.4 | Enable debounce time (switch to high) | Over- or undervoltage | 5 | t_{DEB5} | 120 | 320 | 500 | μs | A |
| 8.5 | Enable delay (switch back to low) | Over- or undervoltage | 5 | t_{DEL5} | | 85 | | ms | A |
| 9 | Relay Driver (RELO) | | | | | | | | |
| 9.1 | Saturation voltage | $I \leq 150\text{ mA}$ | 1 | V_{SAT1} | 0.1 | | 0.5 | V | A |
| 9.2 | Current limitation | | 1 | I_{LIM} | 150 | | 300 | mA | A |
| 9.3 | Internal clamping voltage | | 1 | V_{CL} | 26 | | 30 | V | A |
| 9.4 | Turn-off energy | | 1 | | 30 | | | mJ | C |
| 9.5 | Leakage current | $V_{Batt} = 16\text{ V}$ $V_{Batt} = 26\text{ V at } 25^{\circ}\text{C}$ | 1 | I_{LEAK1} I_{LEAK1} | | | 20 200 | μA μA | A |
| 10 | Power-FET Output FETO (Maximum Load Capacitor at FET Gate 470 pF, Charge-pump Frequency 110 to 300 kHz) | | | | | | | | |
| 10.1 | Output voltage | $V_S = 9\text{ V to } 15\text{ V}$ | 9 | V_{OUT9} | $V_S + 10\text{ V}$ | | $V_S + 15\text{ V}$ | V | A |
| 10.2 | Operation range | | 7 | V_S | 9 | | 20 | V | A |
| 10.3 | Overvoltage shut-down | | 7 | V_S | 20 | | 24 | V | A |
| 10.4 | Internal clamping voltage | | 9 | V_{CL} | 26 | | 30 | V | A |
| 10.5 | On/off frequency | | 9 | f | | | 200 | Hz | A |
| 10.6 | Maximum current | FETO | 9 | I_{FETO} | 10 | | | μA | A |
| 11 | Battery Supply | | | | | | | | |
| 11.1 | Internal clamping voltage | | 7 | V_{CL} | 26 | | 30 | V | A |
| 11.2 | Clamping current capability ⁽¹⁾ | | 7 | I_{VS} | 5 | | | mA | A |
| 11.3 | Leakage current | at FETI = low | 7 | I_{LEAVS} | | | 100 | μA | A |
| 12 | Reset and V_{CC} Control | | | | | | | | |
| 12.1 | Lower reset level | Reference SGND | 14 | V_{CC} | 4.5 | | 4.75 | V | A |
| 12.2 | Upper reset level | Reference SGND | 14 | V_{CC} | 5.25 | | 5.5 | V | A |
| 12.3 | Hysteresis | | 14 | V_{HYST14} | 25 | | 100 | mV | A |
| 12.4 | Reset debounce time | | 14 | t_{DEB} | 120 | 320 | 500 | μs | A |
| 12.5 | Reset delay | | 14 | t_{DEL} | 20 | 50 | 80 | ms | A |

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Note: 1. If $V_S > 26\text{ V}$ the current has to be limited at 5 mA by an external resistor.

Electrical Characteristics (Continued)

$V_{CC} = 5\text{ V}$, $T_{amb} = -40\text{ to }+125^{\circ}\text{C}$; reference pin is GND or SGND (over- and under-voltage detection);
 $f_{intern} = 200\text{ kHz } +50\%/-45\%$, $f_{WDC} = 5\text{ kHz } \pm 10\%$; $f_{WDI} = 50\text{ Hz}$, bootstrap capacitor $C_{Boot} = 47\text{ nF}$ at Pin CAPI

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
|-----------|---|--|-----|----------------|-------|------|-------|---------------|-------|
| 13 | Reset and 3.3 V Control | | | | | | | | |
| 13.1 | Lower reset level | Reference SGND | 16 | $V_{3.3V}$ | 2.97 | | 3.13 | V | A |
| 13.2 | Upper reset level | Reference SGND | 16 | $V_{3.3V}$ | 3.47 | | 3.63 | V | A |
| 13.3 | Hysteresis | | 16 | V_{HYST16} | 15 | | 70 | mV | A |
| 13.4 | Reset debounce time | | 16 | t_{DEB16} | 120 | 320 | 500 | μs | A |
| 13.5 | Reset delay | | 16 | t_{DEL16} | 20 | 50 | 80 | ms | A |
| 13.6 | Current | | 16 | $I_{3.3V}$ | | | 0.5 | mA | C |
| 14 | RC Oscillator WDC | | | | | | | | |
| 14.1 | Oscillator frequency | $R_{OSC} = 36\text{ k}\Omega$ $C_{OSC} = 6.8\text{ nF}$ | 10 | f_{WDC} | 4.5 | 5 | 5.5 | kHz | A |
| 15 | Watchdog Timing | | | | | | | | |
| 15.1 | Power-on-reset prolongation time | | | t_{POR} | 34.3 | | 103.1 | ms | A |
| 15.2 | Detection time for RC-oscillator fault | $V_{CR} = \text{constant}$ | | $t_{RCerror}$ | 81.9 | | 246 | ms | A |
| 15.3 | Time interval for over/under-voltage detection | | | $t_{D,OUV}$ | 0.16 | | 0.64 | ms | A |
| 15.4 | Reaction time of reset output at over/under voltage | | | $t_{R,OUV}$ | 0.187 | | 0.72 | ms | A |
| 15.5 | Nominal frequency for WDI | $f_{RC} = 100 f_{WDI}$ | | f_{WDI} | 10 | | 65 | Hz | D |
| 15.6 | Nominal frequency for WDC | $f_{WDI} = 1/100 f_{WDC}$ | | f_{WDC} | 1 | | 6.5 | kHz | D |
| 15.7 | Minimum pulse duration for a guaranteed WDI input-pulse detection | $f_{WDC} = 5\text{ kHz}$ | | $t_{P,WDI}$ | 364 | | | μs | A |
| 15.8 | Frequency range for a correct WDI signal | $f_{WDC} = 5\text{ kHz}$ | | f_{WDI} | 32.35 | | 56.25 | Hz | D |
| 15.9 | Number of incorrect WDI trigger counts for locking the outputs | | | n_{lock} | | 3 | | | A |
| 15.10 | Number of correct WDI trigger counts for releasing the outputs | | | $n_{release}$ | | 3 | | | A |
| 15.11 | Detection time for a stucked WDI signal | $V_{WDI} = \text{constant}$ $f_{WDC} = 5\text{ kHz}$ | | $t_{WDIerror}$ | 49 | | 51 | ms | A |

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Note: 1. If $V_S > 26\text{ V}$ the current has to be limited at 5 mA by an external resistor.

Electrical Characteristics (Continued)

$V_{CC} = 5\text{ V}$, $T_{amb} = -40\text{ to }+125^{\circ}\text{C}$; reference pin is GND or SGND (over- and under-voltage detection);
 $f_{intern} = 200\text{ kHz } +50\%/-45\%$, $f_{WDC} = 5\text{ kHz } \pm 10\%$; $f_{WDI} = 50\text{ Hz}$, bootstrap capacitor $C_{Boot} = 47\text{ nF}$ at Pin CAPI

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
|-----------|---|-----------------------------|-----|--------|------|------|------|--------|-------|
| 16 | Watchdog Timing Relative to f_{WDC} | | | | | | | | |
| 16.1 | Minimum pulse duration for a guaranteed WDI input-pulse detection | | | | | 2 | | cycles | A |
| 16.2 | Frequency range for a correct WDI signal | | | | 80 | | 170 | cycles | D |
| 16.3 | Hysteresis range at the WDI ok margins | | | | | 1 | | cycle | A |
| 16.4 | Detection time for a stucked WDI signal (WDI dropout) | $V_{WDI} = \text{constant}$ | | | 250 | | 251 | cycles | A |

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Note: 1. If $V_S > 26\text{ V}$ the current has to be limited at 5 mA by an external resistor.

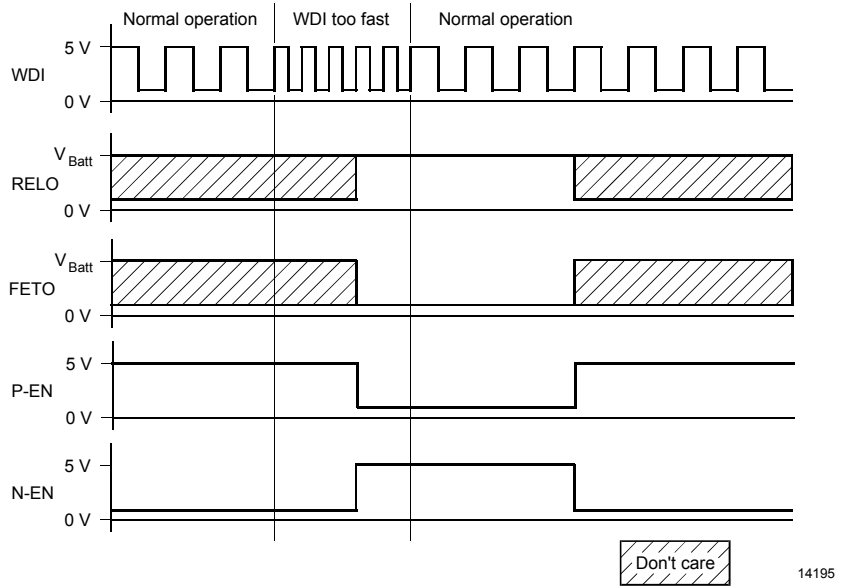
Table 2. Protection Versus Transient Voltages According to ISO TR 7637-1 Level 4 (Except Pulse 5)

| Pulse | Voltage | Source Resistance ⁽¹⁾ | Rise Time | Duration | Amount |
|-------|---------|----------------------------------|-----------|-------------------|--------|
| 1 | - 110 V | 10 Ω | 100 V/s | 2 ms | 15.000 |
| 2 | + 110 V | 10 Ω | 100 V/s | 0.05 ms | 15.000 |
| 3a | - 160 V | 50 Ω | 30 V/ns | 0.1 μs | 1 h |
| 3b | + 150 V | 50 Ω | 20 V/ns | 0.1 μs | 1 h |
| 5 | 55 V | 2 Ω | 10 V/ms | 250 ms | 20 |

Note: 1. In the case of the relay driver, the coil resistance of $R_{min} = 150\ \Omega$ has to be added to the source resistance.

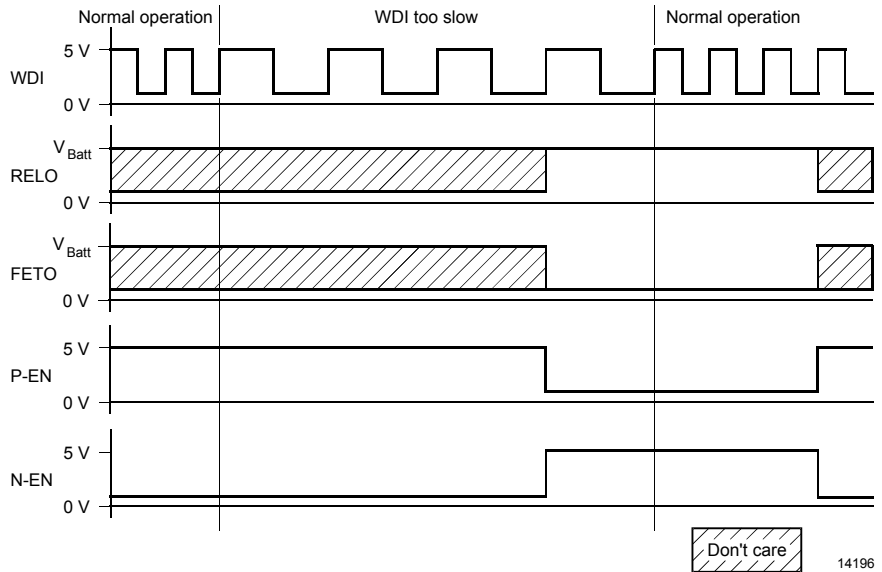
Timing Diagrams

Figure 6. Watchdog in Too-fast Condition



14195

Figure 7. Watchdog in Too-slow Condition



14196

Figure 8. Overvoltage Condition

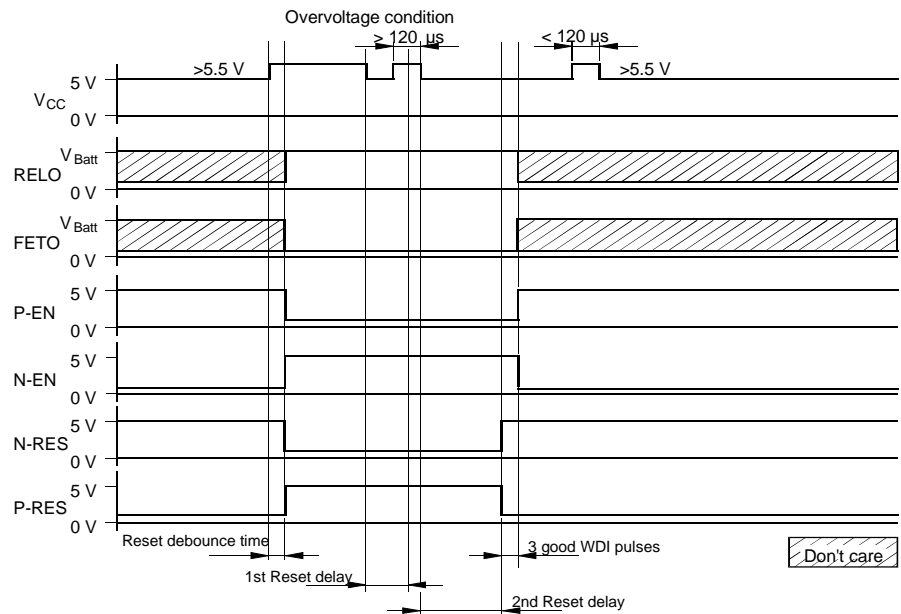


Figure 9. Undervoltage Condition

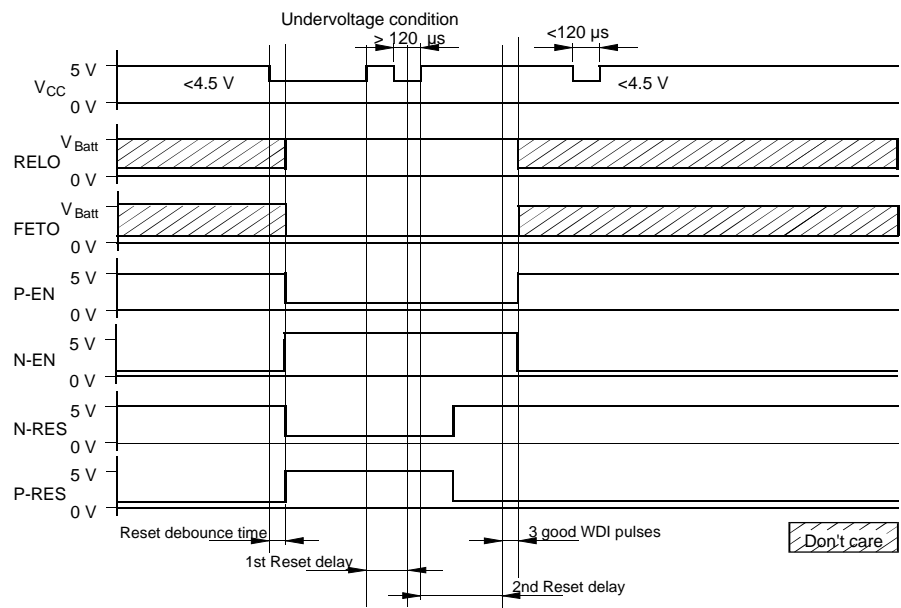
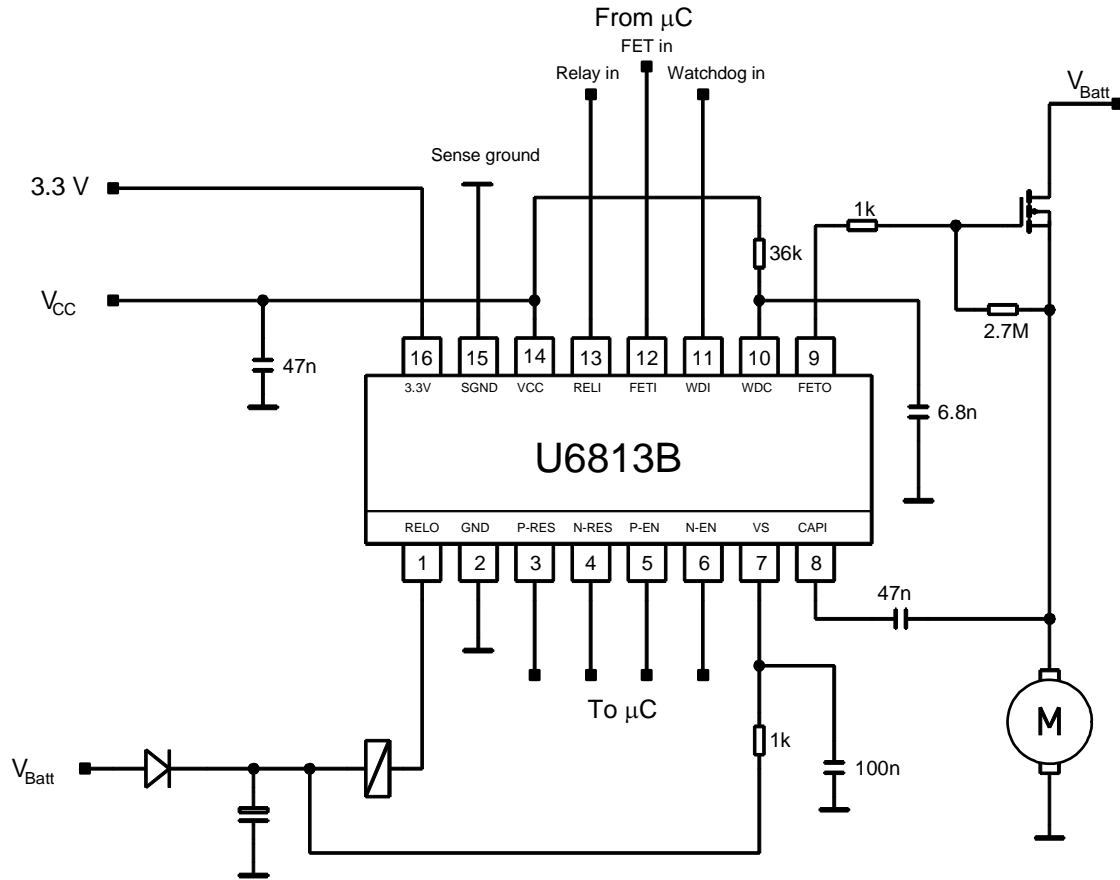


Figure 10. Application Circuit

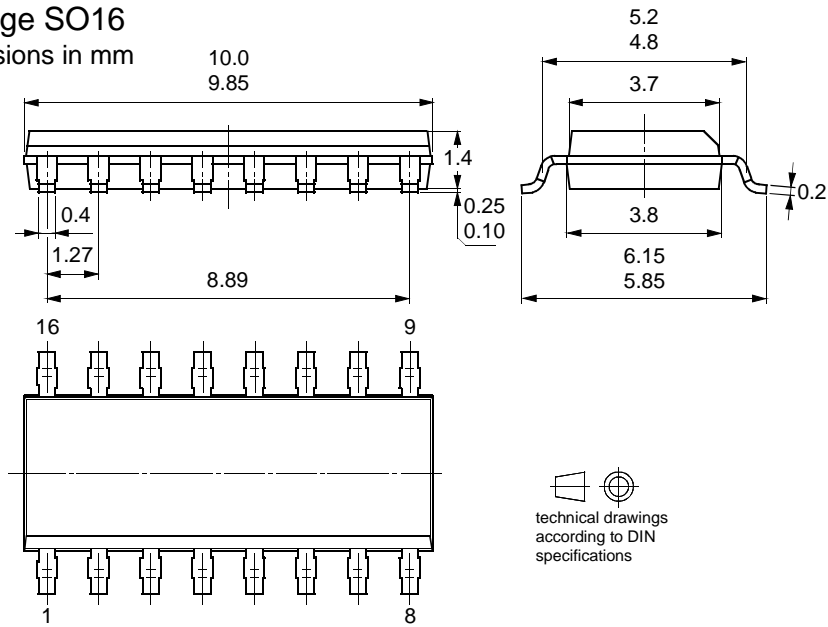


Ordering Information

| Extended Type Number | Package | Remarks |
|----------------------|---------|------------------|
| U6813B-MFPG3 | SO16 | Taped and reeled |

Package Information

Package SO16
Dimensions in mm





Atmel Headquarters

Corporate Headquarters
2325 Orchard Parkway
San Jose, CA 95131
TEL 1(408) 441-0311
FAX 1(408) 487-2600

Europe

Atmel Sarl
Route des Arsenaux 41
Case Postale 80
CH-1705 Fribourg
Switzerland
TEL (41) 26-426-5555
FAX (41) 26-426-5500

Asia

Room 1219
Chinachem Golden Plaza
77 Mody Road Tsimhatsui
East Kowloon
Hong Kong
TEL (852) 2721-9778
FAX (852) 2722-1369

Japan

9F, Tonetsu Shinkawa Bldg.
1-24-8 Shinkawa
Chuo-ku, Tokyo 104-0033
Japan
TEL (81) 3-3523-3551
FAX (81) 3-3523-7581

Atmel Operations

Memory

2325 Orchard Parkway
San Jose, CA 95131
TEL 1(408) 441-0311
FAX 1(408) 436-4314

Microcontrollers

2325 Orchard Parkway
San Jose, CA 95131
TEL 1(408) 441-0311
FAX 1(408) 436-4314

La Chantrerie
BP 70602
44306 Nantes Cedex 3, France
TEL (33) 2-40-18-18-18
FAX (33) 2-40-18-19-60

ASIC/ASSP/Smart Cards

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FAX (33) 4-42-53-60-01

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906
TEL 1(719) 576-3300
FAX 1(719) 540-1759

Scottish Enterprise Technology Park
Maxwell Building
East Kilbride G75 0QR, Scotland
TEL (44) 1355-803-000
FAX (44) 1355-242-743

RF/Automotive

Theresienstrasse 2
Postfach 3535
74025 Heilbronn, Germany
TEL (49) 71-31-67-0
FAX (49) 71-31-67-2340

1150 East Cheyenne Mtn. Blvd.
Colorado Springs, CO 80906
TEL 1(719) 576-3300
FAX 1(719) 540-1759

Biometrics/Imaging/Hi-Rel MPU/ High Speed Converters/RF Datacom

Avenue de Rochepleine
BP 123
38521 Saint-Egreve Cedex, France
TEL (33) 4-76-58-30-00
FAX (33) 4-76-58-34-80

e-mail

literature@atmel.com

Web Site

<http://www.atmel.com>

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