## CMOS Analog Clock IC with Alarm Function

## OVERVIEW

The CF5761 series are analog clock ICs with alarm functions that derive their timing from a standard 32.768 kHz oscillator element. Two kinds of alarm output are available and can be selected using a control pin. The series lineup comprises devices with various alarm patterns and motor outputs for a wide range of clock specifications. They support convenient functions, such as input chattering elimination circuit and power-on clear functions. They are fabricated using Molybdenum-gate CMOS process, realizing low power consumption.

## FEATURES

- 32.768 kHz fundamental frequency oscillator
- Feedback resistor and oscillator capacitor $C_{D}$ built-in
- Supports various alarms: piezo-alarm, electromagnetic speaker
- Snooze function
- Switchable alarm function using SEL pin
- Alarm auto-stop function (see series lineup)
- Input chattering elimination circuit (SEL, AI, SN)
- Test function
- 1.2 to 3.6 V operating supply voltage
- Chip form (CF5761××)
- Molybdenum-gate CMOS process


## PAD LAYOUT

(Unit: $\mu \mathrm{m}$ )


## ORDERING INFORMATION

| Device | Package |
| :---: | :---: |
| CF5761×× | Chip form |

## SERIES LINEUP

|  |  | CF5761CA |  |  |  |  |  | CF5761EA |  |  |  |  |  | CF5761HA |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Built-in capacitance ${ }^{1}$ | $\mathrm{C}_{\mathrm{G}}[\mathrm{pF}]$ | 4 |  |  |  |  |  | 4 |  |  |  |  |  | 4 |  |  |  |  |  |
|  | $\mathrm{C}_{\mathrm{D}}[\mathrm{pF}]$ | 27 |  |  |  |  |  | 27 |  |  |  |  |  | 27 |  |  |  |  |  |
| Motor output | Active level | - |  |  |  |  |  | LOW |  |  |  |  |  | LOW |  |  |  |  |  |
|  | Needle period $\mathrm{t}_{\mathrm{CY}}[\mathrm{s}]$ | 0.0625 (8Hz sweep) |  |  |  |  |  | 1 |  |  |  |  |  | 10 |  |  |  |  |  |
|  | Pulsewidth tpw [ms] | 62.5 (50\% duty) |  |  |  |  |  | 23.4 |  |  |  |  |  | 13.7 |  |  |  |  |  |
| Al input | Active level | HIGH (pull-down) |  |  |  |  |  | HIGH (pull-down) |  |  |  |  |  | HIGH (pull-down) |  |  |  |  |  |
|  | Bounce delay [ms] | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  |
| SN input | Active level | HIGH (pull-down) |  |  |  |  |  | HIGH (pull-down) |  |  |  |  |  | HIGH (pull-down) |  |  |  |  |  |
|  | Snooze time $\mathrm{t}_{\text {SNZ }}[\mathrm{s}]$ | 300 |  |  |  |  |  | 300 |  |  |  |  |  | 300 |  |  |  |  |  |
|  | Bounce delay [ms] | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  |
| Alarm output | SEL pin | LOW |  |  | HIGH |  |  | LOW |  |  | HIGH |  |  | LOW |  |  | HIGH |  |  |
|  | Application | Simple alarm |  |  | Simple alarm |  |  | Step tone alarm |  |  | Simple alarm |  |  | Simple alarm |  |  | Simple alarm |  |  |
|  |  | A01, AO3: tone AO2: motor bell |  |  | A01, AO3: tone AO2: Magnet speaker |  |  | A01, AO2: motor bell |  |  | A01, AO2: motor bell |  |  | AO1, AO3: tone |  |  | AO1, AO3: tone |  |  |
|  | Pin | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 |
|  | Active level | H | H | L | 64 Hz clock output | H | 32 Hz <br> clock <br> output | H | L | $\begin{gathered} 32 \mathrm{kHz} \\ \text { F } \\ \text { output } \end{gathered}$ | H | L | $\begin{gathered} 32 \mathrm{kHz} \\ \text { F } \\ \text { output } \end{gathered}$ | H | H | L | H | H | L |
|  | Frequency fpw [kHz] | 4 | DC | 4 |  | 2 |  | - | - |  | DC | DC |  | 4 | - | 4 | 4 | - | 4 |
|  | Modulation ${ }^{\mathrm{f}} \mathrm{CY}$ [Hz] | 8 | - | 8 |  | 8 |  | 1+2+4+8 | 1+2+4+8 |  | - | - |  | 1+16 | 1+16 | 1+16 |  | - |  |
|  |  | - | - | - |  | - |  | 1+2+8 | 1+2+8 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | 1+8 | 1+8 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | DC | DC |  | - | - |  | - | - | - |  | - |  |
|  | Duty [\%] | 50 | - | 50 |  | 50 |  | 50 | 50 |  | - | - |  | 50 | - | 50 |  | - |  |
|  |  | - | - | - |  | - |  | 50 | 50 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | 50 | 50 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | - | - |  | - | - |  | - | - | - |  | - |  |
|  | Step time [s] | - | - | - |  | - |  | 0-8 | 0-8 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | 8-16 | 8-16 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | 16-24 | 16-24 |  | - | - |  | - | - | - |  | - |  |
|  |  | - | - | - |  | - |  | 24- | 24- |  | - | - |  | - | - | - |  | - |  |
|  | Auto-stop [s] | None |  |  |  |  |  | None |  |  |  |  |  | None |  |  |  |  |  |
|  | $\mathrm{I}_{\mathrm{OH}}[\mathrm{mA}]$ min. | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.01 | -0.01 | -0.9 | -0.01 | -0.01 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 |
|  | $\mathrm{I}_{\text {OL }}$ [mA] min. | 0.9 | 0.01 | 0.9 | 0.9 | 0.01 | 0.9 | 0.01 | 0.9 | 0.01 | 0.01 | 0.9 | 0.01 | 0.9 | 0.01 | 0.9 | 0.9 | 0.01 | 0.9 |

1. $C_{G}$ and $C_{D}$ built-in parasitic capacitance $\left(C_{G}=C_{D}=4 p F\right)$

|  |  | CF5761LB |  |  |  |  |  | CF5761MB |  |  |  |  |  | CF5761NB |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Built-in capacitance $^{1}$ | $\mathrm{C}_{\mathrm{G}}[\mathrm{pF}]$ | 4 |  |  |  |  |  | 4 |  |  |  |  |  | 4 |  |  |  |  |  |
|  | $\mathrm{C}_{\mathrm{D}}[\mathrm{pF}]$ | 34 |  |  |  |  |  | 34 |  |  |  |  |  | 34 |  |  |  |  |  |
| Motor output | Active level | LOW |  |  |  |  |  | - |  |  |  |  |  | LOW |  |  |  |  |  |
|  | Needle period $\mathrm{t}_{\mathrm{CY}}[\mathrm{s}]$ | 1 |  |  |  |  |  | 0.0625 (8Hz sweep) |  |  |  |  |  | 1 |  |  |  |  |  |
|  | Pulsewidth $\mathrm{t}_{\text {PW }}$ [ms] | 31.3 |  |  |  |  |  | 62.5 (50\% duty) |  |  |  |  |  | 23.4 |  |  |  |  |  |
| Al input | Active level | LOW (pull-up) |  |  |  |  |  | LOW (pull-up) |  |  |  |  |  | LOW (pull-up) |  |  |  |  |  |
|  | Bounce delay [ms] | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  |
| SN input | Active level | LOW (pull-up) |  |  |  |  |  | LOW (pull-up) |  |  |  |  |  | LOW (pull-up) |  |  |  |  |  |
|  | Snooze time ${ }_{\text {SNZ }}[\mathrm{s}]$ | 300 |  |  |  |  |  | 300 |  |  |  |  |  | 300 |  |  |  |  |  |
|  | Bounce delay [ms] | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  | 62.5 |  |  |  |  |  |
| Alarm output | SEL pin | LOW |  |  | HIGH |  |  | LOW |  |  | HIGH |  |  | LOW |  |  | HIGH |  |  |
|  | Application | Step volume alarm |  |  | Simple alarm |  |  | Step volume alarm |  |  | Simple alarm |  |  | Step volume alarm |  |  | Step volume alarm |  |  |
|  |  | A01, AO2: tone |  |  | A01, AO2: motor bell |  |  | A01, A02: tone |  |  | A01, AO2: motor bell |  |  | A01, AO2: tone |  |  | A01, AO2: tone |  |  |
|  | Pin | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 | A01 | AO2 | AO3 |
|  | Active level | H | L | Not used | H | H | Not used | H | L | Not used | H | H | Not used | H | L | Not used | H | L | Not used |
|  | Frequency fPW [kHz] | 2 | 2 |  | DC | DC |  | 2 | 2 |  | DC | DC |  | 4 | 4 |  | 2 | 2 |  |
|  | Modulation ${ }^{\mathrm{f}} \mathrm{CY}[\mathrm{Hz}]$ | 1+8 | 1+8 |  | - | - |  | 1+8 | 1+8 |  | - | - |  | 1+8 | 1+8 |  | 1+8 | 1+8 |  |
|  |  | 1+8 | 1+8 |  | - | - |  | $1+8$ | 1+8 |  | - | - |  | 1+8 | $1+8$ |  | 1+8 | $1+8$ |  |
|  |  | 1+8 | 1+8 |  | - | - |  | 1+8 | 1+8 |  | - | - |  | 1+8 | 1+8 |  | 1+8 | 1+8 |  |
|  |  | - | - |  | - | - |  | 1+8 | 1+8 |  | - | - |  | - | - |  | - | - |  |
|  | Duty [\%] | 6.25 | 6.25 |  | - | - |  | 6.25 | 6.25 |  | - | - |  | 6.25 | 6.25 |  | 12.5 | 12.5 |  |
|  |  | 12.5 | 12.5 |  | - | - |  | 12.5 | 12.5 |  | - | - |  | 12.5 | 12.5 |  | 25 | 25 |  |
|  |  | 50 | 50 |  | - | - |  | 25 | 25 |  | - | - |  | 50 | 50 |  | 50 | 50 |  |
|  |  | - | - |  | - | - |  | 50 | 50 |  | - | - |  | - | - |  | - | - |  |
|  | Step time [s] | 0-8 | 0-8 |  | - | - |  | 0-4 | 0-4 |  | - | - |  | 0-8 | 0-8 |  | 0-8 | 0-8 |  |
|  |  | 8-16 | 8-16 |  | - | - |  | 4-8 | 4-8 |  | - | - |  | 8-16 | 8-16 |  | 8-16 | 8-16 |  |
|  |  | 16- | 16- |  | - | - |  | 8-12 | 8-12 |  | - | - |  | 16- | 16- |  | 16- | 16- |  |
|  |  | - | - |  | - | - |  | 12- | 12- |  | - | - |  | - | - |  | - | - |  |
|  | Auto-stop [s] | 300 |  |  |  |  |  | 300 |  |  |  |  |  | 300 |  |  |  |  |  |
|  | $\mathrm{l}_{\mathrm{OH}}[\mathrm{mA}]$ min. | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 | -0.9 |
|  | ${ }^{1} \mathrm{OL}$ [mA] min. | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 | 0.9 |

1. $\mathrm{C}_{\mathrm{G}}$ and $\mathrm{C}_{\mathrm{D}}$ built-in parasitic capacitance $\left(\mathrm{C}_{\mathrm{G}}=\mathrm{C}_{\mathrm{D}}=4 \mathrm{pF}\right)$

## BLOCK DIAGRAM



## PAD DESCRIPTION and DIMENSIONS

| Number | Name | 1/0 | Function | Pad dimensions |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\mathrm{X}[\mu \mathrm{m}]$ | $\mathrm{Y}[\mu \mathrm{m}]$ |
| 1 | 01 | 0 | Movement motor drive output 1 (CMOS output) | 155 | 1215 |
| 2 | 02 | 0 | Movement motor drive output 2 (CMOS output) | 155 | 1023 |
| 3 | VSS | - | Ground | 155 | 835 |
| 4 | AO2 | 0 | Alarm output 2 | 155 | 567 |
| 5 | A01 | 0 | Alarm output 1 | 155 | 155 |
| 6 | A03 | 0 | Alarm output 3 | 351 | 155 |
| 7 | SEL | 1 | Alarm function select. Pull-down resistor built-in | 583 | 155 |
| 8 | XTN | 0 | Crystal oscillator output. Oscillator capacitance $\mathrm{C}_{\mathrm{D}}$ built-in | 1255 | 166 |
| 9 | XT | 1 | Crystal oscillator input. Crystal connected between XT and XTN | 1255 | 399 |
| 10 | SN | 1 | Snooze input <br> Pull-down resistor built-in (CF5761CA, EA, HA) Pull-up resistor built-in (CF5761LB, MB, NB) | 1255 | 587 |
| 11 | AI | 1 | Alarm input <br> Pull-down resistor built-in (CF5761CA, EA, HA) Pull-up resistor built-in (CF5761LB, MB, NB) | 1255 | 821 |
| 12 | T1 | I/O | Test pin | 1217 | 1215 |
| 13 | VDD | - | Supply | 1029 | 1215 |

## SPECIFICATIONS

## Absolute Maximum Ratings

| Parameter | Symbol | Condition | Rating | Unit |
| :--- | :---: | :---: | :---: | :---: |
| Supply voltage range | $\mathrm{V}_{\mathrm{DD}}-\mathrm{V}_{S S}$ |  | -0.3 to 5.0 | V |
| Input voltage range | $\mathrm{V}_{\mathrm{IN}}$ |  | $\mathrm{V}_{S S}$ to $\mathrm{V}_{\mathrm{DD}}$ | V |
| Operating temperature range | $\mathrm{T}_{\mathrm{opr}}$ | -30 to 80 | ${ }^{\circ} \mathrm{C}$ |  |
| Storage temperature range | $\mathrm{T}_{\text {stg }}$ |  | -65 to 150 | ${ }^{\circ} \mathrm{C}$ |

## Electrical Characteristics

### 1.5V operation

$\mathrm{T}_{\mathrm{a}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{SS}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{X}^{\prime} \operatorname{tal}\left(\mathrm{f}_{0}=32.768 \mathrm{kHz}, \mathrm{C}_{\mathrm{I}}=35 \mathrm{k} \Omega\right.$ max, $\left.\mathrm{C}_{\mathrm{G}}=20 \mathrm{pF}\right)$ unless otherwise noted

| Parameter | Symbol | Condition | Rating |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | min | typ | max |  |
| Operating voltage | $V_{D D}$ |  | 1.2 | 1.5 | 3.6 | V |
| Oscillator startup time ${ }^{1}$ | $t_{1}$ | $V_{D D}=1.2 \mathrm{~V}$ | - | - | 5.0 | S |
| Frequency voltage characteristic | $\Delta \mathrm{f} / \mathrm{f}$ |  | - | - | 1.0 | ppm/0.1V |
| Current consumption ${ }^{1}$ | $I_{D D}$ | No output load | - | 0.5 | 1.0 | $\mu \mathrm{A}$ |
|  |  | No output load, F output | - | 0.9 | 1.8 |  |
| 01, 02 motor output current ${ }^{2}$ | IOUT | $\mathrm{V}_{\mathrm{DD}}=1.2 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=400 \Omega$ | 2.40 | 2.55 | - | mA |
| AI HIGH-level input current | $\mathrm{I}_{\mathrm{H} 1}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=1.5 \mathrm{~V}$ | 0.6 | 3 | 7.5 | $\mu \mathrm{A}$ |
| AI LOW-level input current | $\mathrm{I}_{\text {LL1 }}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | 0.6 | 3 | 7.5 | $\mu \mathrm{A}$ |
| SN, SEL HIGH-level input current | $\mathrm{I}_{\mathrm{H} 2}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{1 \mathrm{H}}=1.5 \mathrm{~V}$ | 0.2 | 1 | 2 | $\mu \mathrm{A}$ |
|  | $\mathrm{I}_{\mathrm{H} 3}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=0.5 \mathrm{~V}$ | 9 | 18 | 36 |  |
| SN LOW-level input current | 1/L2 | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | 0.2 | 1 | 2 | $\mu \mathrm{A}$ |
|  | ILL3 | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=1.0 \mathrm{~V}$ | 9 | 18 | 36 |  |
| AO1, AO2, AO3 LOW-level output current ${ }^{3}$ | IOL1 | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{OL}}=0.75 \mathrm{~V}$ | 900 | 2000 | - | $\mu \mathrm{A}$ |
|  | $\mathrm{l}_{\text {OL2 }}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{OL}}=0.75 \mathrm{~V}$ | 10 | 30 | 100 |  |
| AO1, AO2, AO3 HIGH-level output current ${ }^{3}$ | IOH 1 | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{OH}}=0.75 \mathrm{~V}$ | 900 | 2000 | - | $\mu \mathrm{A}$ |
|  | $\mathrm{I}_{\mathrm{OH} 2}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{OH}}=0.75 \mathrm{~V}$ | 10 | 30 | 100 |  |
| T1 LOW-level output current | Iolt | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{OL}}=1.5 \mathrm{~V}$ | 5 | 10 | 20 | $\mu \mathrm{A}$ |
| T1 HIGH-level output current | $\mathrm{I}_{\text {OHT }}$ | $\mathrm{V}_{\mathrm{DD}}=1.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{OH}}=0 \mathrm{~V}$ | 5 | 10 | 20 | $\mu \mathrm{A}$ |
| F output voltage ${ }^{4}$ | $V_{F}$ | $V_{D D}=1.2 \mathrm{~V}$, output capacitance $C_{L}=50 \mathrm{pF}$ | 0.4 | - | - | V |
| Built-in capacitance | $C_{\text {D }}$ |  | See series lineup |  |  | pF |

1. Measured using standard circuits.
2. $\mathrm{R}_{\mathrm{L}}$ is the resistance of the motor coil connected between O 1 and O 2 .
3. The rating varies depending on the device selected. Please refer to the series lineup table for details.
4. F output voltage is the difference voltage, with load capacitor $\mathrm{C}_{\mathrm{L}}$ connected between F and VSS pins, between $0.5 \mathrm{~V}_{D D}$ and the peak voltage.

### 3.0V operation

$\mathrm{T}_{\mathrm{a}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{SS}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{X}$ 'tal $\left(\mathrm{f}_{0}=32.768 \mathrm{kHz}, \mathrm{C}_{\mathrm{I}}=35 \mathrm{k} \Omega\right.$ max, $\left.\mathrm{C}_{\mathrm{G}}=20 \mathrm{pF}\right)$ unless otherwise noted

| Parameter | Symbol | Condition | Rating |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | min | typ | max |  |
| Operating voltage | $\mathrm{V}_{\mathrm{DD}}$ |  | 1.2 | 3.0 | 3.6 | V |
| Oscillator startup time ${ }^{1}$ | $t_{1}$ | $V_{D D}=2.4 \mathrm{~V}$ | - | - | 5.0 | $s$ |
| Frequency voltage characteristic | $\Delta \mathrm{f} / \mathrm{f}$ |  | - | - | 1.0 | ppm/0.1V |
| Current consumption ${ }^{1}$ | $I_{D D}$ | No output load | - | 0.6 | 1.2 | $\mu \mathrm{A}$ |
|  |  | No output load, F output | - | 1.3 | 2.6 |  |
| 01, 02 motor output current ${ }^{2}$ | Iout | $\mathrm{V}_{\mathrm{DD}}=2.4 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$ | 2.26 | - | - | mA |
| AI HIGH-level input current | $\mathrm{I}_{\mathrm{H} 1}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=3.0 \mathrm{~V}$ | 0.6 | 3 | 7.5 | $\mu \mathrm{A}$ |
| AI LOW-level input current | $\mathrm{I}_{\text {L1 }}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\text {IL }}=0 \mathrm{~V}$ | 0.6 | 3 | 7.5 | $\mu \mathrm{A}$ |
| SN, SEL HIGH-level input current | $\mathrm{I}_{\mathrm{H} 2}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=3.0 \mathrm{~V}$ | 0.2 | 1 | 2 | $\mu \mathrm{A}$ |
|  | $\mathrm{I}_{\mathrm{H} 3}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=0.5 \mathrm{~V}$ | 25 | 50 | 100 |  |
| SN LOW-level input current | 1/L2 | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | 0.2 | 1 | 2 | $\mu \mathrm{A}$ |
|  | IIL3 | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=2.5 \mathrm{~V}$ | 25 | 50 | 100 |  |
| AO1, AO2, AO3 LOW-level output current ${ }^{3}$ | $\mathrm{l}_{0,1}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{OL}}=1.5 \mathrm{~V}$ | 900 | - | - | $\mu \mathrm{A}$ |
|  | $\mathrm{l}_{\text {OL2 }}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{OL}}=1.5 \mathrm{~V}$ | 10 | - | - |  |
| AO1, AO2, AO3 HIGH-level output current ${ }^{3}$ | $\mathrm{I}_{\mathrm{OH} 1}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{OH}}=1.5 \mathrm{~V}$ | 900 | - | - | $\mu \mathrm{A}$ |
|  | $\mathrm{I}_{\mathrm{OH} 2}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{OH}}=1.5 \mathrm{~V}$ | 10 | - | - |  |
| T1 LOW-level output current | IoLt | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{OL}}=3.0 \mathrm{~V}$ | - | 20 | - | $\mu \mathrm{A}$ |
| T1 HIGH-level output current | $\mathrm{I}_{\text {OHT }}$ | $\mathrm{V}_{\mathrm{DD}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{OH}}=0 \mathrm{~V}$ | - | 20 | - | $\mu \mathrm{A}$ |
| F output voltage ${ }^{4}$ | $V_{F}$ | $V_{D D}=2.4 \mathrm{~V}$, output capacitance $\mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$ | 0.8 | - | - | V |
| Built-in capacitance | $C_{\text {D }}$ |  | See series lineup |  |  | pF |

1. Measured using standard circuits.
2. $\mathrm{R}_{\mathrm{L}}$ is the resistance of the motor coil connected between O 1 and O 2 .
3. The rating varies depending on the device selected. Please refer to the series lineup table for details.
4. F output voltage is the difference voltage, with load capacitor $\mathrm{C}_{\mathrm{L}}$ connected between F and VSS pins, between $0.5 \mathrm{~V}_{\mathrm{DD}}$ and the peak voltage.

## Measurement Circuit


$X^{\prime}$ tal $f_{0}=32.768 \mathrm{kHz}, \mathrm{C}_{\mathrm{I}}=35 \mathrm{k} \Omega \max , \mathrm{C}_{\mathrm{L}}=12.5 \mathrm{pF}, \mathrm{C}_{0}=1.3 \mathrm{pF}, \mathrm{C}_{1}=2.6 \mathrm{pF}, \mathrm{C}_{\mathrm{G}}=20 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=400 \Omega$ or $1 \mathrm{k} \Omega$

## FUNCTIONAL DESCRIPTION

## Motor Output

The CF5761 series comprise devices with different step movement and sweep movement cycles and pulsewidths.

| Parameter | CF5761CA | CF5761EA | CF5761HA | CF5761LB | CF5761MB | CF5761NB |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Active level | - | LOW | LOW | LOW | - | LOW |
| Movement cycle $\mathrm{t}_{\mathrm{CY}}[\mathrm{s}]$ | 0.0625 | 1 | 10 | 1 | 0.0625 | 1 |
| Pulsewidth tPW $[\mathrm{ms}]$ | 62.5 | 23.4 | 13.7 | 31.3 | 62.5 | 23.4 |
| Movement | Sweep | Step | Step | Step | Sweep | Step |

## Step movement



## Sweep movement



## Alarm Control

The alarm is controlled using AI, SN, and SEL inputs. These pins have built-in chattering elimination circuits to prevent incorrect operation due to input chatter. The alarm output timing in response to these inputs is shown in the following figure.

| Input | Function | Input chatter elimination |
| :---: | :---: | :---: |
| AI | Alarm control input. <br> When Al is active, the specified alarm pattern is output on $\mathrm{AO1}, \mathrm{AO} 2$ and AO 3 . | $\mathrm{t}_{\mathrm{ON}}<62.5 \mathrm{~ms}$, the input is not accepted. $\mathrm{t}_{\mathrm{ON}}>125 \mathrm{~ms}$, the input is accepted. $62.5 \mathrm{~ms} \leq \mathrm{t}_{\mathrm{ON}} \leq 125 \mathrm{~ms}$, the input state is undefined. |
| SN | Snooze function control input. <br> When the snooze input is accepted, the snooze time count begins. The snooze time is 300 s . |  |
| SEL | Alarm function select input. <br> Selects one of two alarm patterns. When SEL is switched (from HIGH to LOW, or LOW to HIGH), the snooze state and auto-stop function is released, and the alarm signal is output. |  |



## Alarm Modes

The CF5761 series provide several alarm modes and various alarm pattern outputs for a wide range of clock specifications, as described in the following table.

| Alarm mode | Mode description | Output | Device |
| :--- | :--- | :--- | :--- |
| Simple alarm | A fixed alarm pattern is repeatedly rung (basic mode). | Motor bell <br> Piezo-electric speaker <br> Electromagnetic speaker | CF5761CA/EA/HA/LB/MB |
| Step tone <br> modulated alarm | At fixed intervals, the alarm pattern changes, increasing the tone pitch <br> with each step. | Motor bell | CF5761EA |
| Step volume <br> modulated alarm | At fixed intervals, using a fixed alarm pattern, the output waveform duty <br> changes, increasing the volume with each step. | Piezo-electric speaker <br> Electromagnetic speaker | CF5761LB/MB/NB |

The alarm pattern timing for each device in the CF5761 series is shown in the series lineup.
The CF5761HA has a special modulated alarm pattern when SEL is HIGH, as shown in the following figure. Outputs AO1 and AO3 have a frequency modulated alarm waveform output at the alarm fundamental frequency of $4 \mathrm{kHz}(4096 \mathrm{~Hz})$. The modulation pattern is output on AO 2 .


## Power-ON Initialization

The CF5761 series are reset to the following conditions after power is applied.

- AI, SN, SEL input state

These inputs are reset to LOW, except where the device has an active-LOW input in which case it is reset to HIGH. See the series lineup table.

- O1, O2

In step movement devices, both outputs are HIGH and subsequent output occurs on O1. In sweep movement devices, O 1 is reset LOW and O 2 is reset HIGH, and output starts immediately.

- $\mathrm{AO} 1, \mathrm{AO} 2, \mathrm{AO} 3$

No output after reset. However, F output (CF5761EA: 32 kHz on AO3) and clock output start immediately.

- Test mode

Test mode is released after reset. Note that after the oscillator starts, the input state of each pin is read and operation commences accordingly.

## Test Function

The CF5761 series have a test mode of operation where the output cycles are compressed. T1 has a built-in chattering elimination circuit to prevent incorrect operation due to input chatter. When T1 goes HIGH for an interval of 31.25 ms or greater, test mode is invoked. When T1 becomes open circuit, normal mode operation resumes immediately and a 256 Hz signal is output on T 1 .

| T1 | Function |
| :---: | :--- |
|  | Motor outputs: In step movement devices, the output runs 16 times faster with normal pulsewidth. In sweep movement devices, <br> the output runs 16 times faster with 50\% duty pulsewidth. <br> Alarm outputs: Alarm operates at the same frequency with modulation frequency 16 times faster and step output changes 8 times <br> faster (CF5761EA, LB, NB) or 4 times faster (CF5761MB). <br> Snooze time, auto-stop time $1: 281.25 m s ~(C F 5761 E A, ~ L B, ~ N B) ~ o r ~ 562.5 m s ~(C F 5761 M B) ~ i n ~ s t e p ~ o u t p u t ~ a l a r m ~ m o d e, ~ a n d ~$ <br> $140.625 m s ~ i n ~ o t h e r ~ m o d e s . ~$ |

1. The auto-stop time applies only to CF5761 versions that support the auto-stop function. See the series lineup table.

## TYPICAL APPLICATION CIRCUITS

## Piezo-electric speaker



## Motor bell



Electromagnetic speaker


Melody alarm


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