## 4-channel H-bridge type BTL driver for CD players <br> BA6299FP

The BA6299FP is a 4-channel H -bridge BTL driver for CD player motors and actuators. The 5 V regulator and internal standard operational amplifier make this IC suited to a broad range of applications.

- Applications

CD players and CD-ROM drives

## - Features

1) HSOP 2B-pin package allows for miniaturization of applications.
2) Wide dynamic range.
3) Low number of external components
4) Driver gain is adjustable with a single attached resistor.
5) Internal 5 V regulator. (requires attached PNP tran sistor)
6) Internal standard operational amplifier.
7) Internal thermal shutdown circuit

## Block diagram


-Pin description

| Pin No. | Pin name | Function |
| :---: | :---: | :---: |
| 1 | VIN1 | Driver channel 1 input |
| 2 | VIN1' | Input for changing driver channel 1 gain |
| 3 | VIN2 | Driver channel 2 input |
| 4 | VIN2' | Input for changing driver channel 2 gain |
| 5 | OPOUT | Operational amplifier output |
| 6 | OPIN- | Operational amplifier negative input |
| 7 | OPIN+ | Operational amplifier positive input |
| 8 | GND | Substrate ground |
| 9 | Vcc | Power supply |
| 10 | BIAS | Bias input |
| 11 | VO2- | Driver channel 2 negative output |
| 12 | VO2+ | Driver channel 2 positive output |
| 13 | VO1- | Driver channel 1 negative output |
| 14 | VO1+ | Driver channel 1 positive output |
| 15 | VO4+ | Driver channel 4 positive output |
| 16 | VO4- | Driver channel 4 negative output |
| 17 | VO3+ | Driver channel 3 positive oulput |
| 18 | VO3- | Driver channel 3 negative output |
| 19 | MUTE | Mute control |
| 20 | Voc | Power supply |
| 21 | GND | Substrate ground |
| 22 | RGND | Regulator ground |
| 23 | REGB | Connect to base of attached transistor |
| 24 | REGOUT | 5 V output (connect to base of attached transistor collector) |
| 25 | VIN3' | Input for changing driver channel 3 gain |
| 26 | VIN3 | Driver channel 3 input |
| 27 | VIN4' | Input for changing driver channel 4 gain |
| 28 | VIN4 | Driver channel 4 input |

Note) Positive outpul' and 'negative output' indicate the phase relative to input.

- Input/output circuit


Fig. 1

- Absolute maximum values $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

| Parameter | Symbol | Limits | Unit |
| :---: | :---: | :---: | :---: |
| Power supply voltage | Vcc | 18 | V |
| Power dissipation | Pd | 1.7*1 | W |
| Operating temperature | Topr | -30~85 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature | Tstg | -55~150 | ${ }^{\circ} \mathrm{C}$ |

* 1 When mounted on $50 \times 50 \times 1.0 \mathrm{~mm}$ phenol paper PCE
Reduced by 13.6 mW for each incresse in Ta of $1^{\circ} \mathrm{C}$ over $25^{\circ} \mathrm{C}$.
-Recommended operating conditions ( $\mathrm{Ta}=25^{\circ} \mathrm{C}$ )

| Parameter | Symbal | Limits | Unit |
| :---: | :---: | :---: | :---: |
| Power supply voltage | Vcc | $6 \sim 11^{* 2}$ | V |
| $* 24 \cdot 11 \mathrm{~V}$ when regulator not used |  |  |  |

Optical disc ICs
-Electrical characteristics (Unless otherwise noted, $\mathrm{Ta}_{\mathrm{a}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}}=8 \mathrm{~V}, \mathrm{RL}=8 \Omega$ )

| Parameter | Symbol | Min. | Typ. | Max. | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| (Driver) |  |  |  |  |  |  |
| Quiescent current | 10 | 2.5 | 5.0 | 7.5 | mA | No load |
| Input offset voltage | $V_{0}$ | -5 | 0 | 5 | mV |  |
| Output offset voltage | $\mathrm{V}_{\infty}$ | -5 | 0 | 5 | mV |  |
| Dead zone width | $\mathrm{V}_{\mathrm{Dg}}$ | 10 | 20 | 30 | mV | (Total for positive and negative) |
| Maximum output amplitude. | Vow | 5.6 | 6.0 | - | V | Differential output |
| Vollage gain | Gve | 7.0 | 9.5 | 11.5 | dB | Vin $=500 \mathrm{mV} \mathrm{DC}$, , differential output |
| Positive and negative voltage differential gain | $\Delta$ Gve | -0.9 | 0 | 0.9 | dB | Vin $=500 \mathrm{mV} \mathrm{DC}$, differential output |
| Ripple rejection | RR | - | 80 | - | dB | $\mathrm{Vin}=0.1 \mathrm{~V} \mathrm{mss}, 100 \mathrm{~Hz}$ |
| Mute-off voltage | Vmoff | 2.0 | - | - | $V$ |  |
| Mute-on voltage | Vmon | - | - | 0.5 | $V$ |  |
| ( 5 V regulator) |  |  |  |  |  |  |
| Output voltage | VaEs | 4.75 | 5.00 | 5.25 | $V$ | $\mathrm{L}=100 \mathrm{~mA}$ |
| Output load variation | $\Delta V_{\text {fl }}$ | -50 | 0 | 10 | mV | $\mathrm{IL}=0 \sim 200 \mathrm{~mA}$ |
| Input variation | $\Delta \mathrm{Vvcc}$ | -10 | 0 | 40 | mV | $(\mathrm{V} C C 666=6 \sim 11 \mathrm{~V}) \mathrm{IL}=100 \mathrm{~mA}$ |
| Drop voltage | Voif | - | 0.3 | 0.6 | V | $\mathrm{V}_{C C}=4.7 \mathrm{~V}, \mathrm{IL}=200 \mathrm{~mA} * 1$ |
| Vreg amplifier output current | latg | 8 | 20 | - | mA | $\mathrm{V}_{C C}=4.7 \mathrm{~V}$, When 3 V is added $* 2$ |
| 〈Operational amplifier) |  |  |  |  |  |  |
| Offset voltage | Vorop | -5 | 0 | 5 | mV |  |
| Input bias current | leop | - | - | 300 | пA |  |
| High-level output voltage | Vatop | 6.5 | 7.2 | - | V |  |
| Low-level output voltage | Valop | - | - | 1.8 | V |  |
| Output drive current (sink) | Isink | 10 | 40 | - | mA | 50@at Voc |
| Output drive current (source) | IsCurc: | 10 | 40 | - | mA | 50@at GND |
| Open loop vollage gain | Gvo | - | 72 | - | dB | Vin $=-75 \mathrm{dBV}$, 1kHz |
| Slew rate | Sf | - | 1 | - | V/us |  |

*2 2 Pin $24=0$ open

- Circuit operation

1. Driver
Inputs to the IC are the focus tracking error signal from the servo preamplifier and the control signal from the motor. The input signals normally center on 2.5 V . Polarity is switched when a signal is greater or less than the bias voltage. When polarity is switched, power
transistors Q1 and Q4 or Q2 and Q3 turn on. Power transistor Q1 or Q3, whichever is turned on, is driven by the full wave rectified signal and the level shifted signal, and supplies current to the load. When there is no input, both output pins are at the GND level.


Fig. 2

This is a typical series regulator that generates a referA standard 4558 type.
ence voltage internally. A PNP Iow saturation transistor must be connected.


Fig. 3

## Application example



Fig. 4
-Operation notes

1. The BA6299FP has an internal thermal shutdown circuit. Output current is muted when the chip temperature exceeds $175^{\circ} \mathrm{C}$ (typically).
2. The output current can be muted when the mute pin (19 pin) voltage is opened or lowered below 0.5 V .
3. Output is muted when the bias pin ( 10 pin ) voltage drops below 1.4 V (typically). Make sure that this $p$ in is at 1.6 V or higher under normal operating conditions.
4. All four driver output channels are muted during thermal shutdown, muting and a drop in bias pin voitage. No other components are muted.
5. Dead zone width is determined as follows: Dead zone width =input resistance $\times 1 \mu \mathrm{~A}$ For this reason, when using the built-in input resistor ( $10 \mathrm{k} \Omega$ ), the dead zone becomes 10 mV (Typ. single-sided). Because input resistance and $1 \mu \mathrm{~A}$
temperature characteristics are canceled, there is virtually no variation due to temperature as long as the internal input resistor is used. However, a dead zone like that defined by the above equation occurs when an external resistor is used to change gain. Temperature change is typically -4600 ppm per degree, and gain change is typically 4600ppm per degree.
6. Be sure to connect the IC to a $0.1 \mu \mathrm{~F}$ bypass capacitor to the power supply, at the base of the IC.
7. Because of the gain adjustment pin's high gain, connecting a long wire to it may result in output oscillation due to free capacitance. Use caution when designing wires.
8. The capacitor between regulator output (24 pin) and GND also serves to prevent oscillation of the IC, so select one with good temperature characteristics.

Thermal derating curve


AMBIENT TEMPERATURE: $T$ ( ${ }^{(C)}$ )
When mounted on $50 \times 50 \times 1.0 \mathrm{~mm}$ phenol paper PCB.

- Electrical characteristics curve

input voltage: Vin (V)

Fig. 6 Driver I/O characleristics (power supply variation)

input voltage: vin (v)

Fig. 7 Driver I/O characteristics (load variation)

infut voltage: yin (v)
Fig. 8 Dead zone l/O characteristics


Fig. 11 Regulator voltage vs temperalure


LORD RESISTANCE: RL ( $\Omega$ )
Fig. 9 Load resistance vs maximum output amplitude


Fig. 10 Driver supply voltage vs voltage gain


Fig. 13 Operational amplifier (open loop characleristics)

External dimensions (Units: mm)


